7. ABSTRACT:

Applicant thanks Examiner for help in identifying excessive word content problems with applicant's abstract of record. Attached is a replacement Abstract. Also attached is a copy of the abstract of record marked up with additions and deletions.

The following is a substitute abstract, no new matter is added.

PRESSURIZED FLUID CONTROLLER USING TILT / PUSH / PULL OPERATOR

Abstract: An intuitive pressurized fluid controller using tilt / push / pull (3 axis) operator includes a swivel joint such that it can move axially and tilt. A first array of valves is arranged to be activated as the lever tilts. A second array of valves is arranged so they can be activated when the lever is pulled axially. A third array of valves is arranged so they can be activated when the lever is pushed axially. When plumbed to a plurality of pressurable positioners supporting heavy equipment, the first array of valves can control the equipment pitch and roll as the lever is tilted, and the second / third arrays of valves can control the equipment elevation as the lever is pulled / pushed.

The following is a marked up copy of the abstract of record, no new matter is added:

PRESSURIZED FLUID CONTROLLER USING TILT / PUSH / PULL OPERATOR

Abstract: An intuitive pressurized fluid controller using tilt / push / pull (3 axis) operator includes a swivel joint "(33)" having a through hole "(14)". A lever "(15)" passes through the hole "(14)" such that it can move axially and as well as tiltably. A first array of valves "(18a, 18b, 18c, 18d)" are is arranged radially to the lever "(15)" axis so they can to be activated either individually or in close pairs as the lever "(15)" is tilts ed. An actuator "(17)" is attached perpendicularly to and further along to the lever "(15)". A second array of valves "(23a, 23b, 23c, 23d)" are is arranged eircularly to and parallel to the lever "(15)" and close to the actuator "(17)" so they can be activated when the lever "(15)" is pulled in it's axial direction axially. A third array of valves "(20a, 20b, 20c, 20d)" are is arranged eircularly to and in opposite parallel alignment to the lever "(15)" and close to the actuator "(17)" so they can be activated when the

lever "(15)" is pushed in it's axial direction axially. Wherein, when When plumbed to a plurality of pressurable positioners "(27a, 27b, 27e, 27d)" supporting a heavy equipment "(24)", the first radial array of valves "(18a, 18b, 18e, 18d)" can control the equipment "(24)" pitch and roll as the lever "(15)" is tilted, and the second and / third arrays of axial valves "(23a, 23b, 23e, 23d and 20a, 20b, 20e, 20d)" can control the equipment "(24)" elevation as the lever "(15)" is pulled and / pushed.

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